Team ALONG

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IJCAI 2020 Mahjong AI Competition

- Chinese Standard Mahjong
- Swiss tournament
- duplicate format
- ranking scores
- 136 tiles, not 8 flowers
- draw tiles from one sub-wall

Features

- base features
 - private hand, concealed Kong, open melds, discarded tiles, and so on
 - unseen tiles and all hand
- look-ahead features
 - distance to each Fan
 - nearest tile pattern for each Fan
- available-action features
 - discard, Chow, Pong, and Kong
 - current tile discarded by others
 - tiles in private hand that are related to Chow

Base Features



Look-ahead Features



- SanSeSanBuGao
- distance 1
- nearest tile pattern



- ZuHeLong
- distance 3
- nearest tile pattern



Network Structure

- one model for all actions
- 50 ResNet blocks
- output policy and value simultaneously

		repeat 50						
593×34 input	256 3×3 conv BatchNorm ReLU	256 3×3 conv BatchNorm ReLU	256 3×3 conv BatchNorm (ReLU)		32 3×3 conv BatchNorm ReLU	1024 → 256 Softm	FC FC nax	
				-	32 3×3 conv BatchNorm ReLU	→ 1024 → 256 Tan	FC FC h	

Action	Discard	Chow	Pong	Kong	Pass
Dim	34	45	1	34	1

Imitation Learning

- behaviour clone
- dataset
 - human data provided by competition organizer
 - about half a million games, 32 million steps
 - filter low-quality data
- training
 - learning rate 0.001, ReduceLROnPlateau
 - batch size 2048

Reinforcement Learning

- PPO+GAE
- reward
 - score
 - Ting
 - Huang
- training
 - start with 100 decks
 - double when the winning rate exceeds 80%

Experiments

- all dataset: filter low-quality data based on human data.
- winner dataset: extract data of winners based on all dataset.
- sl_all model: train on all dataset.
- sl_winner model: train on winner dataset.
- rl_random model: train on random decks based on sl_all model.
- rl_double model: train on double decks based on rl_random model.

Experiments

• imitation learning

Dataset	Batch Size	Acc	Winner Acc	Score
	128	71.96	-	-0.31
All	512	73.21	-	+0.13
	2048	74.00	-	+0.25
	128	70.90	74.58	-
Winner	512	71.33	76.82	-
	2048	72.75	78.68	-

Experiments

• reinforcement learning



Thanks